

CALL FOR APPLICATIONS: RESEARCHER

Job/position/grant:

Job reference:	AE2023-0471 (MinelO - CRAS)
	INESC TEC - Instituto de Engenharia de Sistemas e Computadores, Tecnologia e Ciência
Job/position/grant:	RESEARCHER
City:	Porto
Research field:	Main: ENGINEERING
	Sub: Electrical engineering

Job summary:

INESC TEC is accepting applications for 1 RESEARCHER job in the Robotics, autonomous systems		
Project:	A Holistic Digital Mine 4.0 Ecosystem	
Scientific Advisor:	José Miguel Almeida	
Start Date:	2024-01-04	
Location:	INESC TEC, Porto, Portugal	

Job description:

Notification of results:

Application submission:

Application period:

Work Area: Robotics, autonomous systems

Project overview: - Explore methods for increasing the autonomy of the UX1-Neo and EVA underwater robotic platforms. - Development of autonomous exploration algorithms, landmark-based navigation algorithms to strengthen navigation in confined environments and for the transport and positioning of underwater sensors. - Preparation of tests and validation of systems developed in operational scenarios. **Objectives:** Extend the capacity for autonomous exploration of Robots and the use of autonomous Robot platforms to transport and precisely position sensors in underwater environments.

robotics. Experience with ROS environment and simulation environments such as gazibo. Funding Entity: on the scope MinelO with reference 101091885 funded by the European Commission under the Horizon Europe program for the period 2021-2027. Type of contract: Uncertain term contract The hiring shall be governed by what is stipulated in the legislation in force regarding uncertain term employment contracts and by INES norms.		
Preference factors: Experience in autonomous underwater robotics in mining environments and field experience with under robotics. Experience with ROS environment and simulation environments such as gazibo. Funding Entity: on the scope MinelO with reference 101091885 funded by the European Commission under the Horizon Europe program for the period 2021-2027. Type of contract: Uncertain term contract The hiring shall be governed by what is stipulated in the legislation in force regarding uncertain term employment contracts and by INES norms. Selection criteria: The selection of the candidates will be based on the following criteria, in descending order of considera a) Relevant Curriculum in the concerned field of this tender b) Proven experience. Selection Jury: President of the Jury: Eduardo Silva; Member: Diana Viegas;	Academic Qualifications:	Master in Electrical Engineering.
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Funding Entity: on the scope MinelO with reference 101091885 funded by the European Commission under the Horizon Europe program for the period 2021-2027. Type of contract: Uncertain term contract The hiring shall be governed by what is stipulated in the legislation in force regarding uncertain term employment contracts and by INES norms. Selection criteria: The selection of the candidates will be based on the following criteria, in descending order of considera a) Relevant Curriculum in the concerned field of this tender b) Proven experience. Selection Jury: President of the Jury: Eduardo Silva; Member: Diana Viegas;	Preference factors:	Experience in autonomous underwater robotics in mining environments and field experience with underwater robotics.
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Selection Jury: Description Between the Selection Jury: Description	Selection criteria:	The selection of the candidates will be based on the following criteria, in descending order of consideration:
Selection Jury: President of the Jury: Eduardo Silva; Member: Diana Viegas;		a) Relevant Curriculum in the concerned field of this tender
Member: Diana Viegas;		b) Proven experience.
	Selection Jury:	President of the Jury: Eduardo Silva;
Member: André Dias;		Member: Diana Viegas;
		Member: André Dias;

The results of the selection process will be sent to the interested by electronic mail.

Electronic form filling in www.inesctec.pt in the section Work with Us



From 2023-11-30 to 2023-12-18